



# Tutorial: Application of Deep Clustering Algorithms

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#### Presenters



Collin Leiber



Claudia Plant



Lukas Miklautz



Christian Böhm

#### Hands-On

- Prepared jupyter notebook with examples
- Implemented in PyTorch and ClustPy



- Collab link for jupyter notebook: <u>https://tinyurl.com/cikm23-clustpy</u>
- Download link for material: <u>https://tinyurl.com/cikm23-material</u>

# ClustPy Package

• Link: <u>https://github.com/collinleiber/ClustPy</u>



- > 20 recently introduced (deep) clustering algorithms implemented in sklearn style → Easy to use and apply
- > 70 benchmarking data sets (e.g., UCI, UCR, Torchvision, MedicalMNIST)
- Many performance metrics and visualization methods



# Outline

- Introduction to Clustering
- Introduction to Deep Clustering
- Application of Deep Clustering Algorithms
- Recent Approaches
- Outlook

# Clustering – Find a "meaningful" grouping

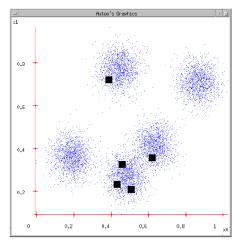


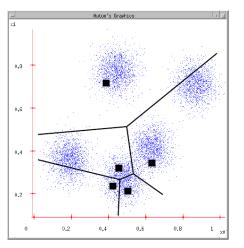






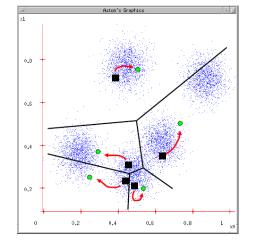
#### Recap: K-Means

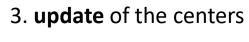


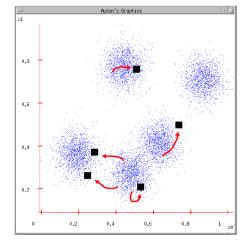


1. random **initialization** of the K cluster centers

2. **assignment** of objects to the closest center







4. iteration of (2) and(3) until convergence

- + fast convergence,
- + well-defined objective function,
- + based on statistical model.

#### Recap: K-Means

Algorithm k-Means

Input Parameter: Number K of clusters; Randomly initialize the K cluster centers  $\mu_1 \dots \mu_K$ Iterate the following steps until convergence: Assign each object  $x_i$  to the nearest centroid  $\mu_j$ Update the cluster centroids  $\mu = (\mu_1 \dots \mu_K)$ 

Objective function:

$$L(\mu; x) = \sum_{i} L(\mu; x_{i}) = \sum_{i} \frac{1}{2} (x_{i} - d_{i}(\mu))^{2}$$

Where the function  $j \coloneqq d_i(\mu)$  assigns the  $i^{th}$  point  $x_i$  to its closest centroid  $\mu_j$ 

#### SGD-K-Means

- Stochastic Gradient Descent Version of K-Means [BB94]
  - Learned parameters for K-Means are the centroids  $\mu_j, j \in \{0, 1, ..., K\}$
  - Runs several times (epochs) over the full data set in randomized order

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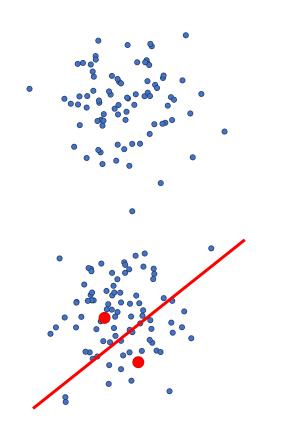
$$L(\mu; x_i) = \frac{1}{2} (x_i - d_i(\mu))^2$$

• The gradient update for the loss function w.r.t.  $\mu$ 

$$\Delta \mu = -\alpha \cdot \frac{\partial L(\mu; x_i)}{\partial \mu} = \begin{cases} \alpha \cdot (x_i - \mu_j), & \text{if } j = d_i(\mu) \\ 0, & \text{otherwise} \end{cases}$$

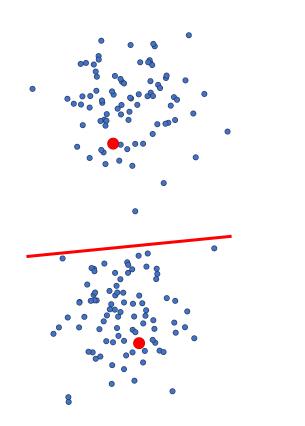
- Each point  $x_i$  moves its respective center  $\mu_i$  closer to  $x_i$  by  $\Delta \mu$
- Optimal learning rate  $\alpha = 1/n_i$  where  $n_i$  is number of objects in cluster j

#### SGD-K-Means converges much faster



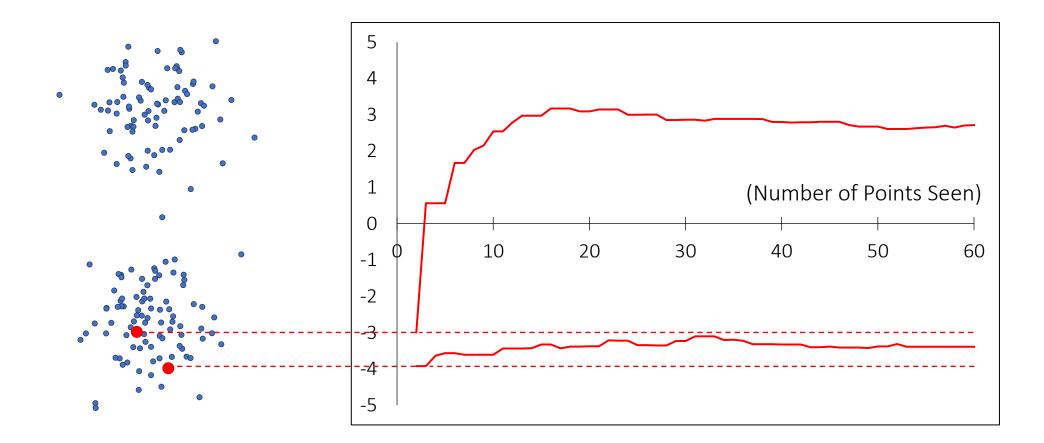
- The random initialization may go wrong
- Classical K-Means would base a complete round of assignment on the resulting boundary

# SGD-K-Means converges much faster



- The random initialization may go wrong
- Classical K-Means would base a complete round of assignment on the resulting boundary
- After having seen e.g. 10 points, the centers are already much better with SGD-K-Means
- SGD-K-Means continuously improves centers

#### SGD-K-Means converges much faster



# Minibatch-K-Means

Algorithm Minibatch-K-Means [S10] Input Parameter: Number K of clusters; Randomly initialize the K cluster centers  $\mu_1 \dots \mu_K$ Iterate the following steps until convergence: Select a Minibatch M; Update centroids  $\mu_1 \dots \mu_K$  for each  $x_i$  in M:  $\Delta \mu = -\alpha \cdot \frac{\partial L(\mu; x_i)}{\partial \mu} = \begin{cases} \alpha \cdot (x_i - \mu_j), & \text{if } j = d_i(\mu) \\ 0, & \text{otherwise} \end{cases}$ 

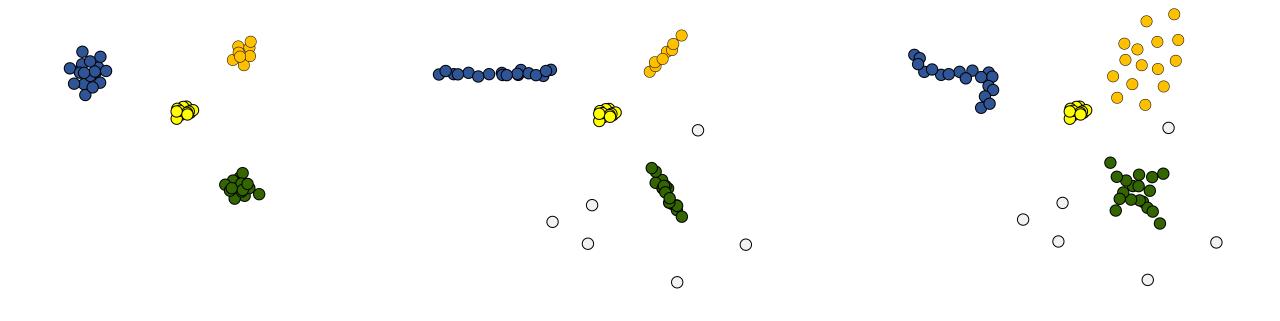
Further improvements, e.g. in [PB10, APB13]:

- Consider additional update of center  $\mu$  whenever the cluster loses a point  $x_i$
- Consider occupation of network/bus when parallel processes exchange information of centers  $\mu_1 \ ... \ \mu_K$

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# The Curse of Dimensionality in Clustering



- Full-dimensional
- Gaussian clusters
- without outliers or noise.

- Subspace clusters
- and outliers.

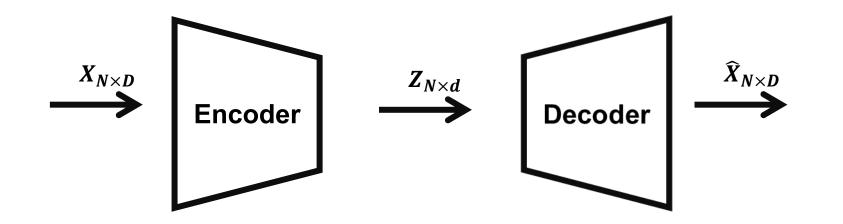
- Arbitrarily shaped subspace clusters,
- of different density,
- noise and outliers.

## Deep Representation Learning

- Successful for image, text, video, audio ...
  - Structured data
  - High data volume
- Automated feature extraction (Representation Learning)
  - Feature engineering requires domain knowledge
- Easy to parallelize
  - GPU friendly
  - Works on large amount of data

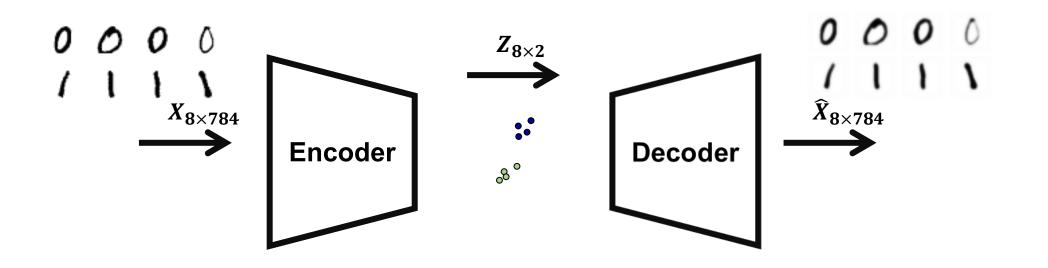
#### Prerequisite: Autoencoder

- Learning is done via self-supervision requires no labels
- The prediction (output) is a reconstruction of the input data
- Goal: Low dimensional representation (embedding) of input data



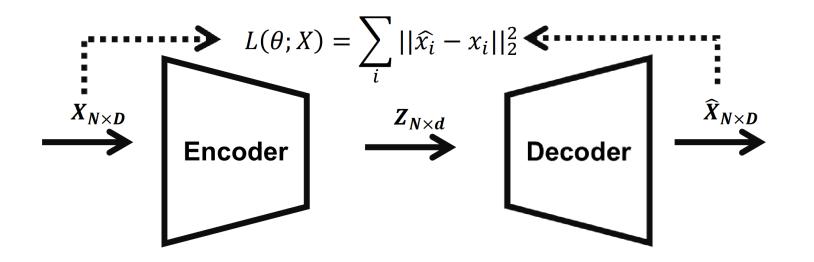
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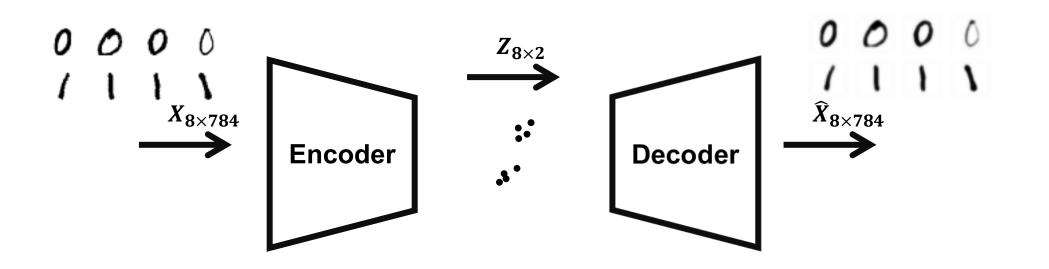
#### Autoencoder – Loss Function

- Compares the reconstruction  $\hat{x}$  with the input x
- Quantifies the reconstruction loss which we want to minimize
- Common choices: Cross Entropy, Sum of Squared Differences



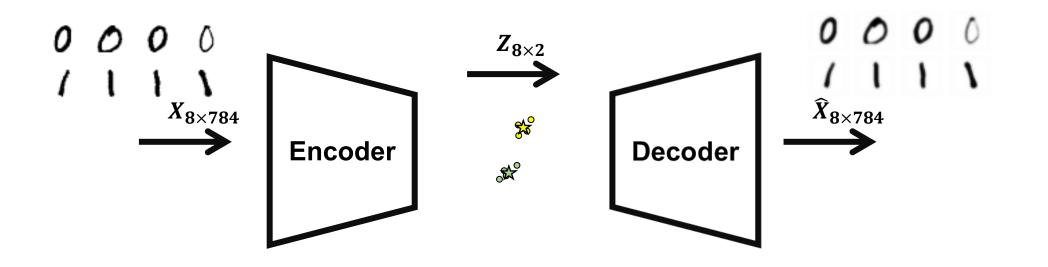
# Sequential Deep Clustering Approach

1) Use an autoencoder to learn a non-linear embedding of your data i.e., Feature learning/Representation learning



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Note: This is not necessarily a bad idea and often useful, but it might limit our solution -> We are stuck to the initial representation

#### Notebook Example

#### • Clustering of Autoencoder embedded space

Ground Truth Centers - Image Space



Ground Truth Centers - Autoencoder

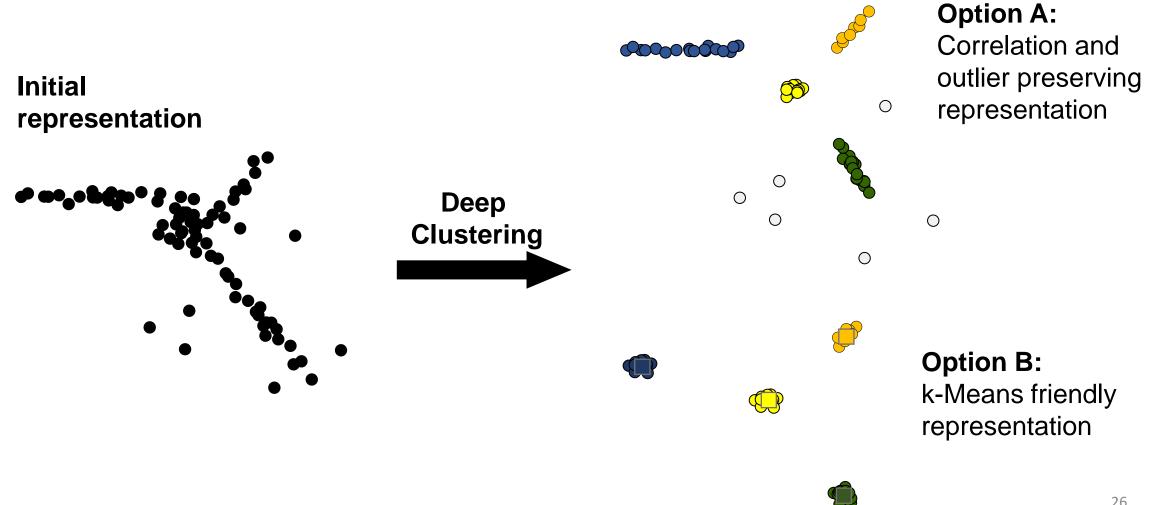


Cluster Centers



# Can we do better?

#### Yes! – Learn A Cluster Friendly Representation



# Deep Clustering - Overview

- Idea: Include the notion of clustering already during the autoencoder training
- Goal: We want to find all relevant cluster structure and improve it!

#### Problems:

- We need to specify a cluster model (inherit assumptions)
- We face circular dependency problem
  - In order to learn a good representation we need to know what clusters we have
  - In order to learn a good clustering we need to have already a good representation
  - Deep Learning is not a magic bullet that solves this problem

# Deep Clustering – Toy Example

- **Problems**: We still face circular dependency problem
  - In order to learn a good representation we need to know what clusters we have
  - In order to learn a good clustering we need to have already a good representation
- Here: Clusters are ripped apart



# Deep Clustering - Approaches

- Alternating optimization
  - Alternate between optimizing the representation and updating the clustering assignments
- Joint optimization
  - Cluster assignments and representation are updated together

# Deep Clustering - Approaches

- Alternating optimization
  - Alternate between optimizing the representation and updating the clustering assignments
- Joint optimization
  - Cluster assignments and representation are updated together
- Overall Goal: Learn a cluster friendly embedding
  - Cluster friendly = Enhanced separation of clusters, Cluster structure is more distinct
  - Increase inter-cluster distance and decrease intra-cluster distance
  - Include structural constraints to avoid the "destruction" of structure, i.e. ripped apart clusters

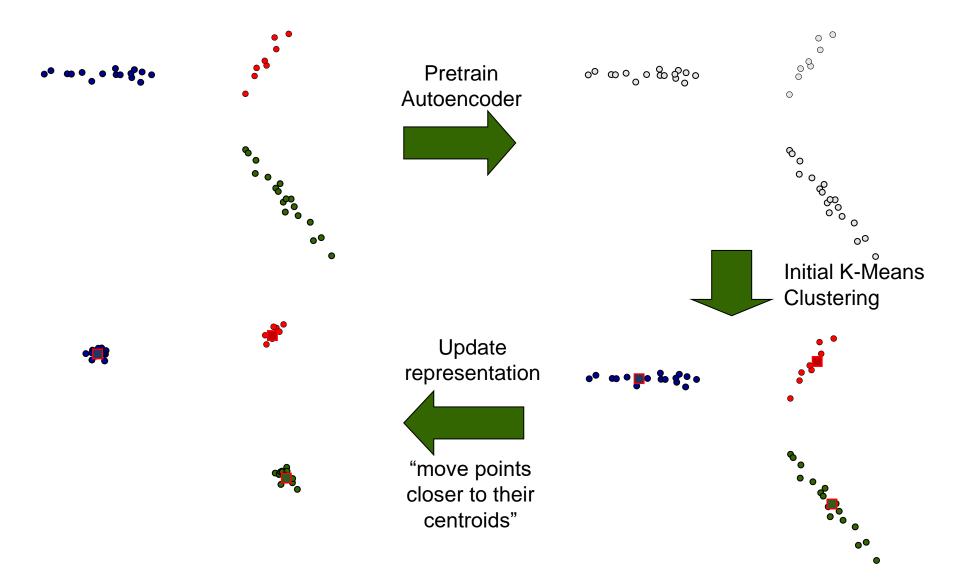
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# Alternating Optimization

- 1) Pretrain an autoencoder to learn a non-linear embedding of your data
  - a) Set the dimensionality to min(k, # features). This "upper bound" avoids losing too much information. For a motivation of this rule of thumb see e.g. the connections of K-means and PCA [DH04]
- 2) Initialize clustering with some algorithm (e.g. K-means)

#### Toy Example – 1 Iteration



# Alternating Optimization

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While cluster labels change:

- a) Fix centroids and update the autoencoder parameters
  - Move points closer to their centroids
- b) Fix autoencoder parameters and update centroids and assignments

# DCN-Deep Clustering Networks

- Deep Clustering Network (DCN) [YFSH17]
  - Based on Mini-Batch K-means [S10]
  - Centroids are not optimized via SGD, but are updated explicitly
  - They use hard cluster assignments which are not differentiable

# DCN-Deep Clustering Networks

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  - Based on Mini-Batch K-means [S10]
  - Centroids are not optimized via SGD, but are updated explicitly
  - They use hard cluster assignments which are not differentiable
- Alternating optimization between clustering and autoencoder
  - Because the calculation of cluster assignments is non-differentiable
  - Alternate between
    - 1) K-Means Step
      - 1) Assignments
      - 2) Centroid updates
    - 2) Autoencoder Step

Preserve Global structure via Reconstruction and make clusters more "K-Means friendly" [YFSH17] by "moving" points closer to their centroids

### DCN-Deep Clustering Networks

- Deep Clustering Network (DCN) [YFSH17]
- Alternating optimization between clustering and autoencoder
  - Alternate between
    - 1) K-Means Step
    - 2) Autoencoder Step (Reconstruction + Compression)

Overall Loss Function  $l = \lambda l_c + l_R$ 

Compression loss:  $l_C = ||z_i - \mu_i||_2^2$ Reconstruction loss:  $l_R = ||\hat{x}_i - x_i||_2^2$ 

where  $\lambda$  is a hyperparameter weighing the importance of cluster structure

#### Notebook Example

#### • Deep clustering with DCN

Ground Truth Centers - Image Space



Ground Truth Centers - Autoencoder



Cluster Centers



#### Joint Optimization

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Jointly optimize the clustering parameters (update centroids and assignments), together with the autoencoder

- Cluster procedure need to be differentiable
- Assignments need to be soft e.g. assignment probabilities
- Usually faster, because we can completely parallelize the procedure

#### DKM - Deep k-Means

- Deep k-Means (DKM) [FTG19]
- Truly joint learning of the representation and the k-Means clustering parameters
- Builds directly on the k-Means loss:

$$\sum_{x \in X} ||x - c(x, M)||_2^2, \text{ where } c(x, M) = \underset{\mu \in M}{\operatorname{argmin}} ||x - \mu||_2^2$$
  
=> For Deep Clustering:  $\mathcal{L} = \sum_{x \in X} \mathcal{L}_{rec}(x) + \lambda ||\operatorname{enc}(x) - c(\operatorname{enc}(x), M)||_2^2$ 

• Problem: *f* must be continuously differentiable!

#### DKM - Deep k-Means

• We need a function 
$$G_k(\mathbf{x}, \alpha, M) = \begin{cases} 1 & \text{if } \mu_k = c(\text{enc}(c), M) \\ 0 & \text{otherwise} \end{cases}$$

• This would lead to: |M|

$$\mathcal{L} = \sum_{x \in X} \mathcal{L}_{rec}(x) + \lambda \sum_{k} ||\operatorname{enc}(x) - \mu_k||_2^2 G_k(\mathbf{x}, \alpha, M)$$

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• Use a parameterized softmax function

$$G_k(\mathbf{x}, \alpha, M) = \frac{e^{-\alpha ||\operatorname{enc}(x) - \mu_k||_2^2}}{\sum_{k'}^{|M|} e^{-\alpha ||\operatorname{enc}(x) - \mu_{k'}||_2^2}}$$

• Formulation is fully differentiable regarding the parameters of the autoencoder and the cluster centers  ${\cal M}$ 

# $\mathsf{DKM} - \mathsf{Deep} \ \mathsf{k} - \mathsf{Means}$ $\bullet \ \mathcal{L} = \sum_{x \in X} \mathcal{L}_{rec}(x) + \lambda \sum_{k}^{|M|} ||\operatorname{enc}(x) - \mu_{k}||_{2}^{2} \frac{e^{-\alpha |\operatorname{enc}(x) - \mu_{k}||_{2}^{2}}}{\sum_{k'}^{|M|} e^{-\alpha |\operatorname{enc}(x) - \mu_{k'}||_{2}^{2}}}$

- For  $\alpha$  close to 0 all centroids are equally weighted, for very large  $\alpha$  it simulates hard cluster assignments
- How to choose a good value for  $\alpha$ ?
  - 1. Possibility
    - Pretrain the autoencoder
    - Start clustering process with a large α (e.g., 1000)
  - 2. Possibility
    - Do not use pretraining
    - Use an annealing strategy for  $\alpha$ .
      - Start with small values and increase  $\alpha$  after a certain amount of epochs

#### Notebook Example

#### • Deep clustering with DKM

Ground Truth Centers - Image Space



Ground Truth Centers - Autoencoder



Cluster Centers



# Coffee Break

# Welcome back. Any questions?

- Deep Embedded Clustering (DEC) [XGF16]
  - Based on SGD-K-means with a student t-kernel for measuring the distance of an embedded data point z<sub>i</sub> to centroid μ<sub>j</sub> in relation to its distance to all other centroids μ<sub>j</sub>, except μ<sub>j</sub>:

$$q_{i,j} = \frac{\left(1 + ||z_i - \mu_j||_2^2\right)^{-1}}{\sum_{j'} \left(1 + ||z_i - \mu_{j'}||_2^2\right)^{-1}} = \frac{distance \ to \ \mu_j}{summed \ distance \ to \ all \ other \ centroids}$$

•  $q_{i,j}$  are soft assignments of the  $i^{th}$  data point to the  $j^{th}$  cluster centroid

- $Q_{N \times K}$  is the matrix of soft assignments  $q_{i,j}$  of N data points to the K centroids
  - Achieved by measuring the distance with the Student's t-kernel between all embedded points  $z_i$  and centroids  $\mu_i$ .

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- Target distribution  $P_{N \times K}$ :

[XGF16] define the following desirable properties for the target distribution P:

- strengthen predictions on data points assigned with high confidence
- normalize loss contribution for each centroid

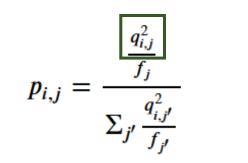
$$p_{i,j} = \frac{\frac{q_{i,j}^2}{f_j}}{\sum_{j'} \frac{q_{i,j'}^2}{f_{j'}}}$$

51

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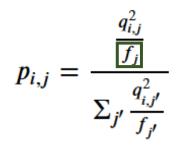
- strengthen predictions on data points assigned with high confidence
- normalize loss contribution for each centroid
- $q_{i,j}^2$  strengthens high confidence predictions
- → Assignments close to one will be kept higher than undecided ones that are close to 0.5



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- strengthen predictions on data points assigned with high confidence
- normalize loss contribution for each centroid
- $q_{i,j}^2$  strengthens high confidence predictions
- $f_j \coloneqq \sum_i q_{i,j}$  (soft) frequency per cluster
- $\rightarrow$  Dividing by  $f_j$  renormalizes by cluster size to avoid that large clusters distort the embedding



• Minimize the KL divergence between the target distribution *P* and the cluster assignment Matrix *Q*:

$$l = l_C = KL(P||Q) = \sum_{i} \sum_{j} p_{i,j} \log\left(\frac{p_{i,j}}{q_{i,j}}\right)$$

• Measures how closely the assignment matrix *Q* matches the target distribution *P* 

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- Measures how closely the assignment matrix  ${\cal Q}$  matches the target distribution  ${\cal P}$
- Overall Intuition Increase separation of clusters by moving embedded points closer to their centroids  $\mu_i$  and repelling points from other centroids  $\mu_j$ ,  $j \neq i$ .
- Note that DEC does not use the reconstruction loss  $l_R$  during the joint optimization process  $^{\rm 55}$

#### Notebook Example

#### • Deep clustering with DEC

Ground Truth Centers - Image Space



Ground Truth Centers - Autoencoder



Cluster Centers



### IDEC-Improved Deep Embedded Clustering

- [GGLY17] proposed to keep the reconstruction loss during joint optimization with DEC to avoid such distorted solutions
- Their approach IDEC uses during the joint optimization both losses

Overall loss function  $l = l_R + \lambda l_c$ 

Compression loss: 
$$l_C = KL(P||Q)$$
  
Reconstruction loss:  $l_R = ||\widehat{x_i} - x_i||_2^2$ 

### IDEC-Improved Deep Embedded Clustering

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- This alleviates to some degree the previous problem, but depends heavily on the hard to tune weighting hyperparameter  $\lambda$
- Introduces a new problem called Feature Drift [MMKK19]
  - The reconstruction loss and the clustering loss have conflicting goals
  - Reconstruction Loss: Preserve the space as best as possible to reconstruct all features of the data
  - Compression Loss: Increase the separation of the clusters and only focus on the most discriminative features

#### Notebook Example

#### • Deep clustering with IDEC

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Ground Truth Centers - Autoencoder



Cluster Centers



#### Results

- Notebook summary
- What worked?
- What could be improved?

#### Results

- Notebook summary
- What worked?
- What could be improved? --> Augmentation

#### Motivation - Augmentation

- Invariant representation learned by the autoencoder
  - Autoencoder learns to ignore certain patterns, i.e., rotations, noise, shifts,...
- Invariances inside a cluster
  - Cluster membership should not change due to spurious patterns i.e., slight rotations, lighting conditions, noise, shifts,...
- Include domain knowledge in the form of augmentation
  - E.g., we know that slight rotations of digits do not change the label assigned to them.
  - Strong rotations might flip the label, e.g., digits 6 and 9

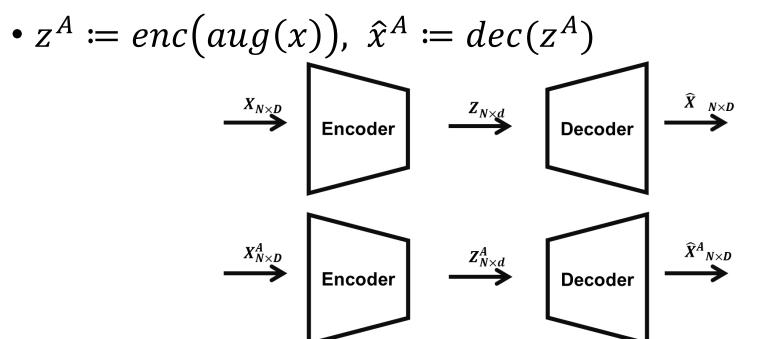
- Cluster membership should not change due to spurious patterns i.e. slight rotations (Invariances inside clusters)
- $x^A \coloneqq aug(x)$  where  $aug(\cdot)$  are different augmentations that we add to the original data point x.

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$$z^A \coloneqq enc(aug(x)), \ \hat{x}^A \coloneqq dec(z^A)$$

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 $\xrightarrow{x_{N \times D}}$ 
Encoder
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- New loss function  $l = l_C^A + l_R^A$   $l_C^A = ||z_i - \mu_i||_2^2 + ||z_i^A - \mu_i||_2^2$  $l_R^A = ||\hat{x}_i - x_i||_2^2 + ||\hat{x}_i^A - x^A||_2^2$

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- $x^A \coloneqq aug(x)$  where  $aug(\cdot)$  are different augmentations that we add to the original data point x.
- $z^A \coloneqq enc(aug(x)), \ \hat{x}^A \coloneqq dec(z^A)$
- New loss function  $l = l_C^A + l_R^A = ||z_i \mu_i||_2^2 + ||z_i^A \mu_i||_2^2$   $l_C^A = ||z_i - \mu_i||_2^2 + ||z_i^A - \mu_i||_2^2$  $l_R^A = ||\hat{x}_i - x_i||_2^2 + ||\hat{x}_i^A - x^A||_2^2$
- We use the cluster assignments and centroids learned from our "clean" examples
- Thus we force the augmented data points to be in the same cluster as their originals

#### Notebook Example

Augmented images



Original images



#### Outline

- Introduction to Clustering
- Introduction to Deep Clustering
- Application of Deep Clustering Algorithms
- Recent Approaches
- Outlook

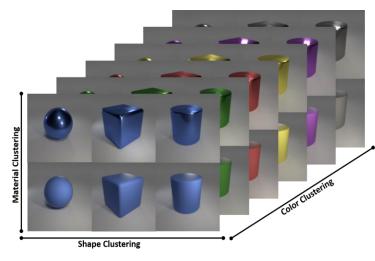
### Specialized Deep Clustering Algorithms

- Flat & Centroid based approaches
  - DEC [XGF16]
  - IDEC [GGLY17]
  - DCN [YFSH17]
  - ACe/DeC [MBMTBP21]
- Spectral Clustering
  - SpectralNet [SSLBNK18]
  - DualAE [YDZYL19]
- Mutual Information
  - IMSAT [HMTMS17]
  - IIC [JHV19]
- Density based
  - DDC [LCCC18]

- Probabilistic Methods
  - ClusterGAN [MALK19]
  - VADE [JYTTZ17]
- Other Approaches
  - Hierarchical Clustering
    - DeepECT [MPB19]
  - Non-Redundant Clustering:
    - ENRC [MMABP20]
  - Subspace Clustering
    - DSC [JZLSR17]
  - K-estimation
    - DipDECK [LBSBP21]

### Deep Non-Redundant Clustering

• Embedded Non-Redundant Clustering algorithm (ENRC) [MMABP20]

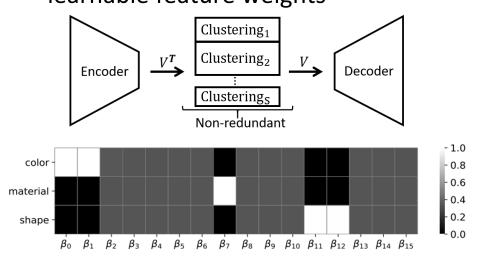


#### Non-redundant clusterings:

- Shapes : Cube, Cylinder, Sphere
- Colors: Red, Blue, Green, Yellow Purple, Grey
- Material: Rubber, Metal

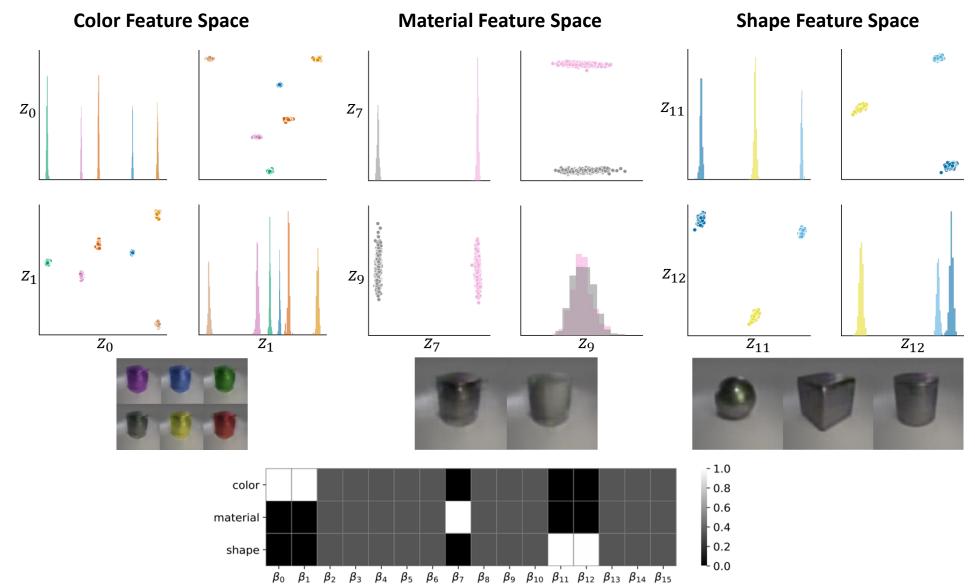
How to find all three clusterings with unsupervised deep learning?

#### → Non-redundant clustering layer: Softly split the embedded space with learnable feature weights



71

#### Deep Non-Redundant Clustering



72

• Deep Embedded Cluster Tree (DeepECT) [MPB19]

Naïve Approach

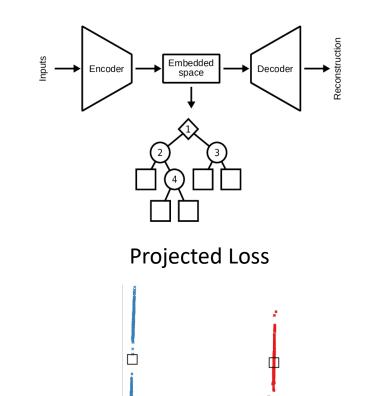
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- Based on Bisecting Kmeans model
- Recursively split embedded space in with k = 2
- Uses projected cluster loss

Example:

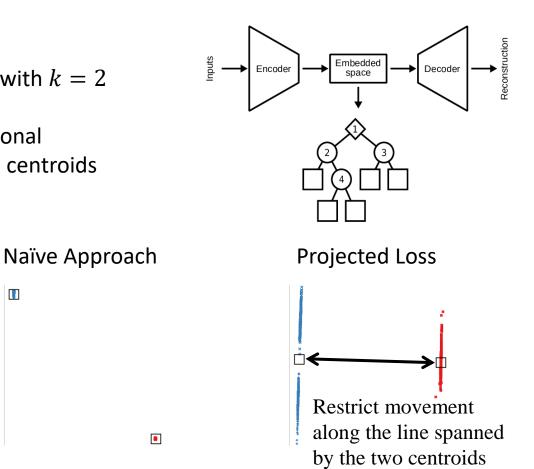
Original

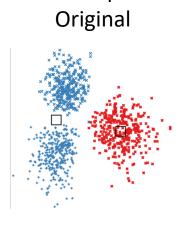
 Preserve structure along orthogonal dimensions spanned by the two centroids



• Deep Embedded Cluster Tree (DeepECT) [MPB19]

- Based on Bisecting Kmeans model
- Recursively split embedded space in with k = 2
- Uses projected cluster loss
  - Preserve structure along orthogonal ٠ dimensions spanned by the two centroids





Example:

74

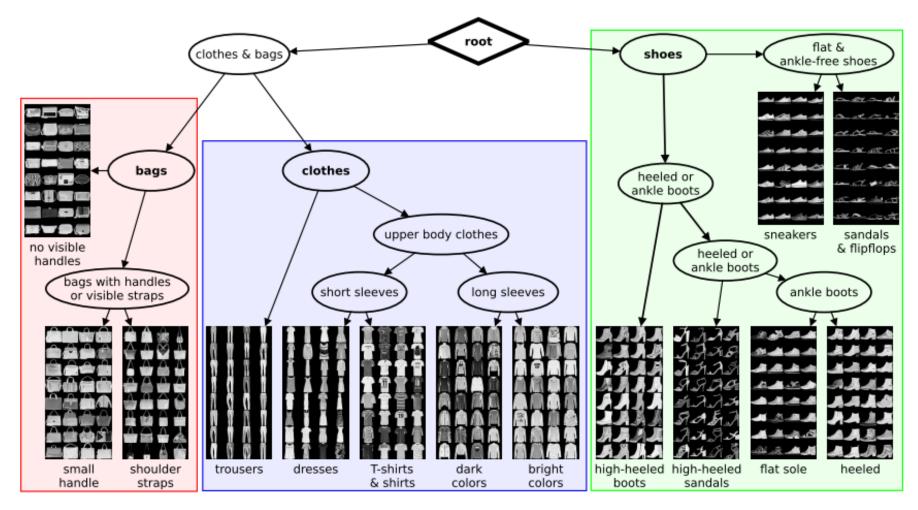
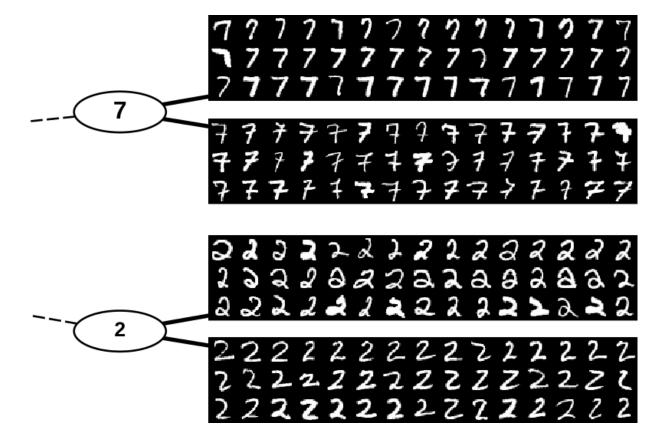


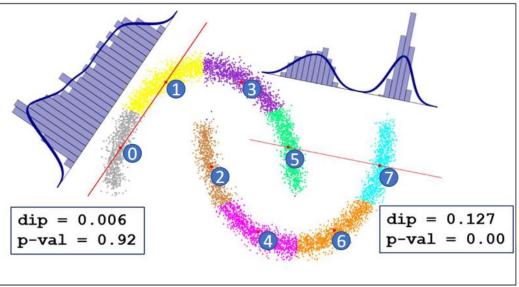
Fig. 2. The diagram shows a cluster tree for the Fashion-MNIST dataset. Each leaf node shows randomly sampled objects assigned to it. The labels are interpretations by the authors. The colored areas highlight the three dominant sub-trees representing three types of objects found in the dataset: bags, clothes, and shoes.

Finding populations and sub-populations and hierarchical structures e.g. different types of 7's and 2's

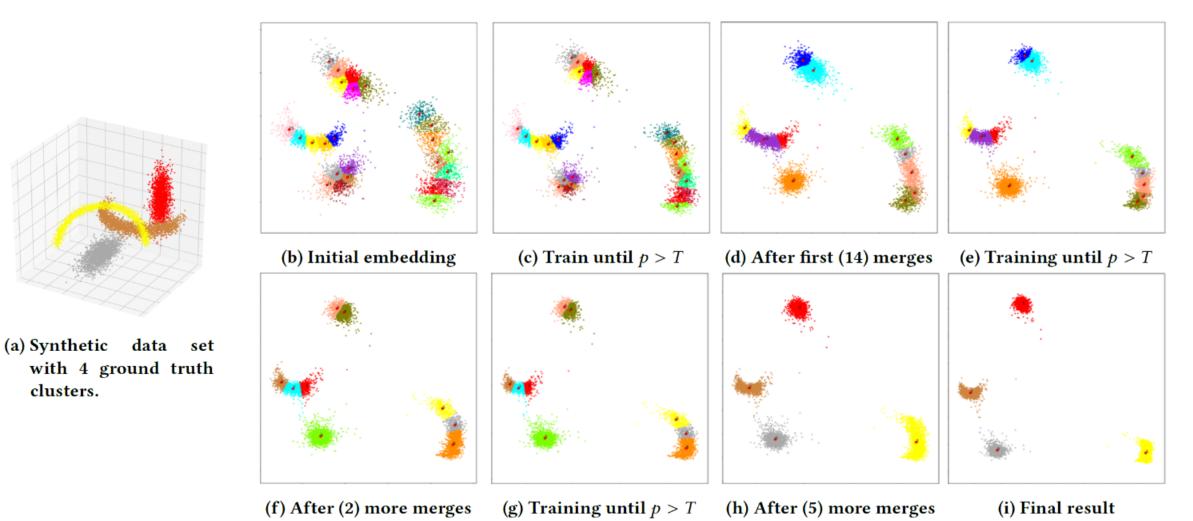


## Deep Clustering with k-estimation

- Dip-based Deep Embedded Clustering with k-estimation (DipDECK) [LBSBP21]
- Problem: 'True' number of clusters is often unknown
- Idea: Overestimate the number of clusters and identify similar microclusters
  - Use Dip-test of unimodality to rate similarity
  - Micro-Clusters describing a common structure should be placed close to each other -> If similarity is high enough, they can be merged



#### Deep Clustering with k-estimation



78

#### Outline

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#### Discussion

- Pros:
  - Finds clusters which are non-linearly hidden in the original space
  - Can find higher "semantic" clusters e.g. digits, traffic signs, ...
  - No need for feature engineering, "only" need to choose an architecture which fits the data type, e.g. convolutional neural nets for image data.
  - Fast inference for clustering unseen data from the same (unknown) distribution
  - Centroids and interpolations in the embedded space can be reconstructed and visualized in the original space.
  - Domain knowledge can be incorporated as data invariances
  - Scales to large amounts of data and dimensions

#### Discussion

#### • Cons:

- Only useful for larger quantities of data
- Works mostly on structured data, e.g., images, sound, text, ...
- Embedded space is hard to interpret (black box optimization)
- Many hyperparameters (number of clusters, learning rate, batch size, architecture, ...)
- Highly dependent on a good initialization (local optima)
- Sensitive to noise and outliers
- Research until now is mostly empirical, no strong theoretical guarantees
- High runtime in comparison to "classical" clustering methods
- Need for specialized hardware (e.g., CUDA enabled GPUs, TPUs, ...)

# In Summary

- Representation learning for clustering (Deep Clustering) is an active research area (about 10 years of research)
- Many interesting algorithms have been proposed transferring "classical" clustering algorithms to the deep learning framework (similar to kernel approaches)
- Many problems of deep learning (e.g., high number of hyperparameters), which can be "easily" tackled in supervised learning are difficult to solve in deep unsupervised learning

## Question for the Audience

• Aside from clustering, in which cases are clustered representations useful?

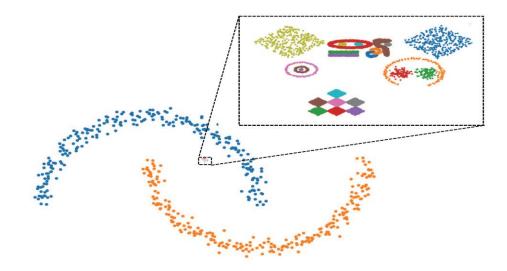
## Question for the Audience

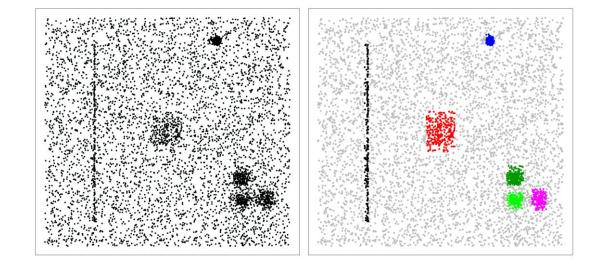
- Aside from clustering, in which cases are clustered representations useful?
  - Some thoughts:
    - In cases where abstraction is of interest, e.g., preserving only prototypical information
      - Simplified representation
      - Representations with less nuisance factors
    - In cases where we want to enforce cluster structure in the representation
      - Information retrieval
      - Task acquisition in meta-reinforcement learning [JHGELF19]
    - Other cases?
- In which might they be less useful?
  - Fine grained classification tasks
  - Generative tasks?
  - ...

## **Open Problems in Deep Clustering**

- Imbalanced clusters
- Adversarial Examples
- Fairness & Explainable AI
- Dependence on hyperparameters

#### Imbalanced Clusters, Noise, Outliers

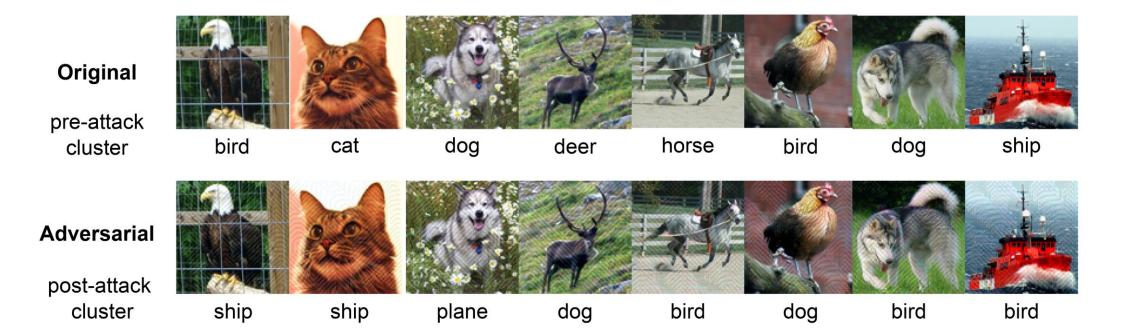




Imbalanced clusters of different scales [DMPB22].

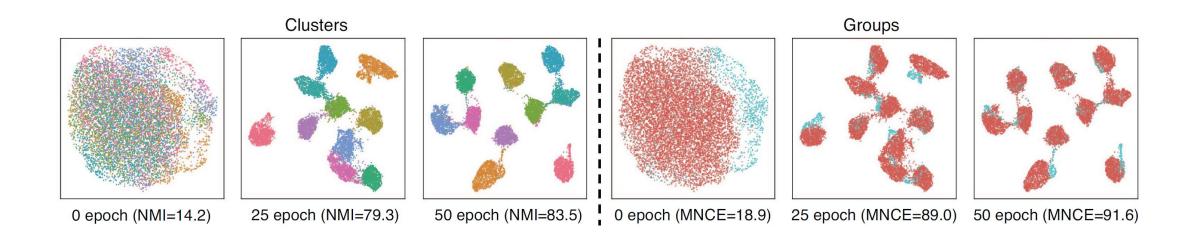
Massive amounts of noise points (80%) [MP16].

#### Adversarial Examples



Slight modifications of the training images learned by a GAN can fool deep clustering methods [CSM22].

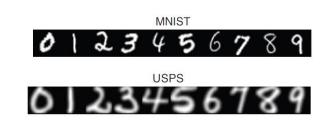
#### Fairness



#### **Challenges:**

- Single user-specified protected attribute,
- Weighting between fairness and quality.

Protected attribute: Data source [ZLHPLP23]



#### Considering the evolution of clustering methods

	High-dimensional data	Interpretability	Runtime	Parameterization
Traditional algorithms, e.g. K- means (1950 and older)		+++	+++	-
Subspace and spectral methods, e.g., NR-K-means [MYPB17] (starting in the 1990ies)	+	++	++	
Deep clustering methods, e.g., ENRC [MMABP20] (popular since 2010)	+++	+		

#### ...hybrid methods might be the future.

	High-dimensional data	Interpretability	Runtime	Parameterization
Traditional clustering algorithms		+++	+++	-
Subspace and spectral methods	+	++	++	
Deep clustering methods	+++	+		
Hybrid methods	+++ expressiveness where needed?	++ interpretable where possible?	+ spend effort where needed?	partly automatic?



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94